Education

Hochschule Bonn-Rhein-Sieg

Sankt Augustin, Germany

M.Sc. in Autonomous Systems

Sept. 2016 - Aug. 2019

 Mathematics for Robotics and Control, Autonomous Mobile Robot, Humanoid Robotics, Evolutionary Algorithm, Neural Networks, Machine Learning, Deep Learning, Software Development, Advance Software Technology, Learning and Adaptivity, Reinforcement Learning, Adaptive Signal Processing

Universitas Trunojoyo Madura

Bangkalan, Indonesia

B.Sc. in Computer Science

Aug. 2010 - Aug. 2014

 Mathematics, Programming (Java, Matlab, C, Pascal), Databases (MySQL, Oracle GlassFish), Web (PHP, JSP), Image Processing, Signal Processing, Artificial Intelligence, Fuzzy Logic, Mobile Games, Computer Graphics.

Extracurricular Activity

b-it-bots RoboCup@Work Team

Sankt Augustin, Germany

Apr. 2017 - Present

ACTIVE MEMBER

- Deployment of machine learning algorithms for robotics applications
- Programmed robots using Python, C++ and Robot Operating Systems (ROS)
- Maintainer of b-it-bots open source projects

SOKET (Trunojoyo Robotics Team)

Bangkalan, Indonesia

MEMBER AND TEAM LEADER IN 2013

Jan. 2011 - Sept. 2014

• Developed robot perception and task planning for mobile and legged firefighting robots

Work Experience _____

Hochschule Bonn-Rhein-Sieg

Sankt Augustin, Germany

Jan. 2020 - Present

RESEARCH ASSOCIATE

- DevOps on E-assessment projects
- SciRoc European Robotics League plus Smart Cities Robot Competitions
- Robotics engineer @b-it-bots

Hochschule Bonn-Rhein-Sieg

Sankt Augustin, Germany

Sept. 2018 - Sept. 2019

- GRADUATE RESEARCH ASSISTANT
- · Large scale JupyterHub deployment for teaching on GKE
- Backend developer for e-assessment projects

PT. Kaber Azeze Mediatel

Sumenep, Indonesia

SOFTWARE ENGINEER (INTERNSHIP)

Jan. 2013 -M Mar. 2013

Developing and maintaining the company website and local networks

Projects

2019 **Point cloud classification of real objects using CNNs**, Master Thesis

Developed real-time multimodal object recognition using point cloud and rgb image, b-it-bots

RoboCup@Work Team

2018 Developed robot perception for advanced welding test, b-it-bots RoboCup@Work Team

2017 Active visual scene exploration for mobile robots, R&D Project

2014 Mobile firefighting robot navigation using Fuzzy logic, Bachelor Thesis

Ski**lls**

Programming

Python, C++, Java, Matlab, C, Bash

Others

GIT, GITHUB, VIM, LINUX, MACHINE LEARNING TOOLS SUCH AS TENSORFLOW, SCIKIT-LEARN, PANDAS, SEABORN

July 4, 2020

b-it-bots: Our Approach for Autonomous Robotics in Industrial Environments

Springer, Cham

Dec. 2019

Honors & Awards

INTERNATIONAL

2019	1st Place, RoboCup@Work German Open and RoboCup@Work	Germany and		
2019	ist Place, Robocup@work definan Open and Robocup@work	Australia		
2018	1st Place - Advanced Welding Test, RoboCup@Work	Montreal, Canada		
2018	2nd Place, RoboCup@Work German Open and RoboCup@Work	Germany and		
		Canada		
		Magdeburg,		
2018	1st Place - Line Tracing and Arbitrary Surface Challenge, RoboCup@Work German Open 1st Place - Navigation and Manipulation Functionalities, European Robotics League - Industrial Robot	Germany		
		Cormany and Italy		
2017	Tournament	Germany and Italy		

REGIONAL

2014	2nd Place Legged Firefighting Robot, Indonesian Robotics Contest - Region 4	Malang, Indonesia
2012	Best Strategy Mobile Firefighting Robot, Indonesian Robotics Contest - Region 4	Surabaya,
2013	best strategy mobile Firefighting Robot, indonesian Robotics Contest - Region 4	Indonesia

Language Proficiency _____

English

FULL PROFESSIONAL PROFICIENCY

Deutsch

LIMITED WORKING PROFICIENCY

JULY 4, 2020 2